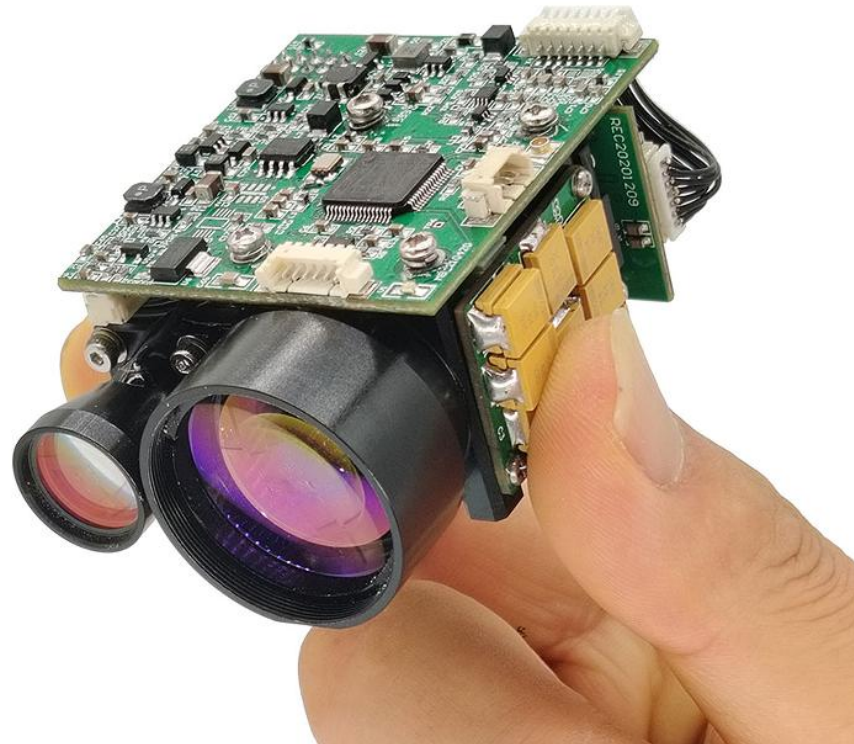


6km Laser Rangefinder Module



Product Introduction

JIO-H0610X laser rangefinder LRF module adopts Jioptik's self-developed 1535nm erbium glass laser component, which has the features of long range, low power consumption, small size and human eye safety.

Ranging performance: 6000m (2.3x2.3m NATO Targets) 10000 m (Large target)

Ranging accuracy $\pm 1m$

Measurement accuracy $\geq 98\%$

Weight $\leq 100g$

Product features

1. Integrated configuration design and front end face multi-point sealing installation, strong anti-imbalance ability, high durability, long working life, eye safety;
2. Using non-thermal receiving optical design technology, with good optical noise suppression ability, near distance ranging performance and high and low temperature optical performance;
3. The internal interface of the circuit adopts the welding wire direct connection process, which is firm and reliable, which can avoid the short circuit or poor contact caused by the loosening, oxidation and water vapor of the connector, and improve the reliability and life of the product.

Product performance index

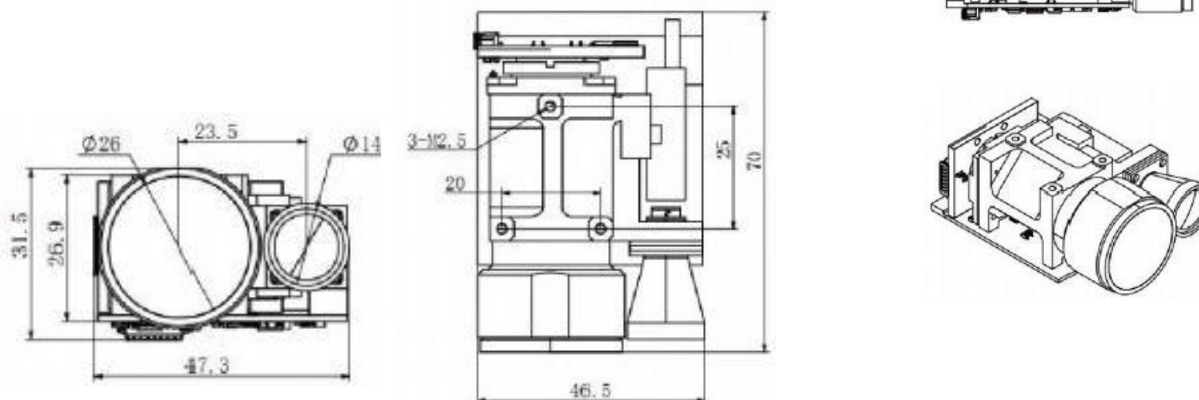
Item	Index	
Model	JIO-H0610X	
Operating wavelength	1535nm $\pm 10nm$	
Eye-Safe	Class 1 (IEC 60825-1)	
Receiving Aperture	$\Phi 25mm$	
Ranging range	30-10000m	
Ranging capability	10000m	Max Ranging(Typical Large targets)
	8000m	Large target, Reflectivity: 60 %,visibility $\geq 25km$
	6000m	Visibility $\geq 25km$, target with 0.3 reflectivity for 2.3m \times 2.3m target
	3000m	1 \times 1 m target,Reflectivity: 10 %,Visibility $\geq 25km$
Communication Interface	RS422	
Humidity	$<80\%$	

Ranging accuracy	±1m
Accuracy rate	≥98%
Divergence angle	≤0.5mrad
Ranging frequency	1~10hz
Continuous ranging time	≥30min
Non-parallelism of the laser optical axis to the mounting reference	<0.3mrad
Size	≤70mm×48mm×32mm
Voltage	9-15V
Power consumption	Standby:<1.5W; Rated:<4W; Peak:<7W
Working temperature	-40℃~+60℃
Storage temperature	-45℃~+70℃
Weight	≤100g

Function:

- 1: With single ranging and continuous ranging function;
- 2: laser out of the number of times the report function
- 3: With multi-target ranging function;

Structure installation interface



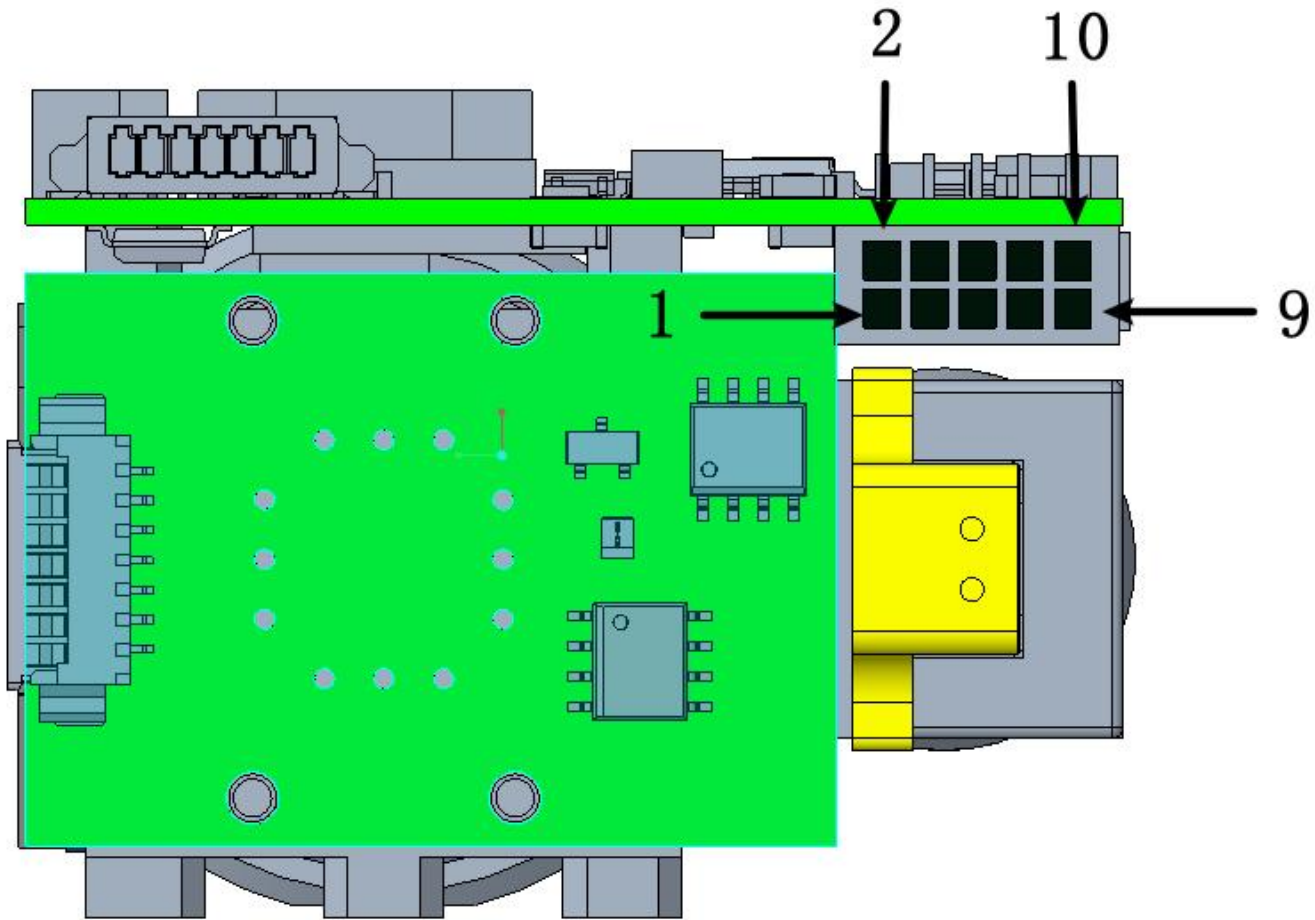
Electrical interface

- a) Communication interface: UART_TTL, RS422, RS232, one of the three options, see Annex 1 for protocol details;
- b) Use PHD-2×5 connector, the interface definition is shown in the table.

Table 3 Electrical Interface Definition

Pin	Interface Type	Definition	Remarks
1	Power Supply	+12V power supply	
2		+12V Power Ground	
3	Communication	RS422-Y(T+)	In respect of this machine
4		RS422-B(R-)	
5		RS422-Z(T-)	
6		RS422-A(R+)	
7	Communication Ground	GND	
8	Communication	UART_TX, RS232_TXD	
9		UART_RX, RS232_RXD	
10	Communication Ground	GND	

Position of pin 1 of connector



Communication protocols

1 Communication rate and format

Format Standards	115200 (factory), N, 8,1, multi-byte data starting high.
Data type	char one byte, int two bytes, long four bytes; signed (default), unsigned.

2 Basic packet format

① Starting character	② Data length	③ Data content	④ Sum check
0xEB	0x90	unsigned char	unsigned char[]
		unsigned char[]	unsigned char

“④ Sum check” refers to the sum of all contents except the checksum, taking the lower 8 bits.

Command data and response data are located in “③ Data content”.

3 Command Data Format

Target device code	Command Code	Additional data of a certain length
unsigned char	unsigned char	unsigned char[]

The time interval between characters should be $\leq 20\text{ms}$.

Normal command codes must not use 0xFF.

4 Response data format

Self device code	Response code	Additional data of a certain length
unsigned char	unsigned char	unsigned char[]
The device should provide a response within 1 second, and the time interval between characters should be $\leq 20\text{ms}$.		
All commands on the bus serial port are responsive.		

5 Device Code

Device Name	Device Code
LRF	0x03

6 response code

Type	Response Code	Additional Data	Meaning	Description
Normal response	Command code	See attachment	Successful execution	Command was processed normally, see device command for additional data.

7.1 Laser self-test

Sent to the laser rangefinder:

bytes	0	1	2	3	4	5
Description	0xEB	0x90	② data length (2)	0x03	0x01	Check_sum

The laser rangefinder returns:

bytes	0	1	2	3	4	5	6	7	8	9
Description	0xEB	0x90	② data length (12)	0x03	0x01	Selfcheck	standby	standby	standby	standby
10	11	12	13	14	15					
standby	standby	standby	standby	standby	standby					

Selfcheckdefine

position	D7	D6	D5	D4	D3	D2	D1	D0
Description	System status: 0: Normal 1: Abnormal					Temperature alarm: 0: Normal 1: Alarm	Bias voltage fault: 0: Normal 1: Fault	Counter malfunction: 0: Normal 1: Fault

7.2 Single ranging

Sent to the LRF:

Bytes	0	1	2	3	4	5
Description	0xEB	0x90	② data length (2)	0x03	0x02	Check_sum

7.3 Automatic ranging

Sent to the LRF:

Bytes	0	1	2	3	4	5
Description	0xEB	0x90	② data length (2)	0x03	0x03	Check_sum

7.4 Stop ranging

Sent to the LRF:

Bytes	0	1	2	3	4	5
Description	0xEB	0x90	② data length (2)	0x03	0x04	Check_sum

7.5 Return distance

LRF single ranging and auto-ranging return automatically by ranging frequency:

Bytes	0	1	2	3	4	5	6	7	8	9
-------	---	---	---	---	---	---	---	---	---	---

Description	0xEB	0x90	② data length (12)	0x03	Single ranging: 0x02 Automatic ranging: 0x03 Standby: 0x00	status	Ranging value 1 integer high 8 bits	Ranging value 1 integer lower 8 bits	Ranging value 1 decimal section	Ranging value 2 integer high 8 digits
10	11	12	13	14	15					
Ranging value 2 integer lower 8 bits	Ranging value 2 decimal places	Ranging value 3 integer high 8 digits	Ranging value 3 integer lower 8 bits	Ranging value 3 decimal sections	Check_sum					

Note: The range value has 2 decimal places.

Status define

position	D7	D6	D5	D4	D3	D2	D1	D0
Description	System status: 0: Normal 1: Abnormal	Front discharge power switch: 0: Close 1: Enable	LD power switch: 0: Close 1: Enable	Bias switch: 0: off 1: On	Working status: 0: Stop 1: Working	Echo state: 0: no echo 1: Echo	Main wave status: 0: without main wave 1: with main wave	Temperature alarm: 0: no alarm 1: alarm

7.6 Setting the frequency

Send to LRF:

Bytes	0	1	2	3	4	5	6
Description	0xEB	0x90	② data length (3)	0x03	0x05	1-5:1-5Hz	Check_sum

Setting parameters LRF return:

Bytes	0	1	2	3	4	5	6	7	8	9
Description	0xEB	0x90	② data length (12)	0x03	0x05: Set frequency 0x08: Query set value	standby	standby	standby	standby	standby
10	11	12	13	14	15	16	17	18	19	20
standby	Ranging frequency 1-5:1-5Hz	Major version number	Secondary version number	Maintenance version number	Check_sum					

7.7 Query Setting Value

Send to laser rangefinder:

Bytes	0	1	2	3	4	5
Description	0xEB	0x90	② data length (2)	0x03	0x08	Check_sum

LRF return:

Same as setup parameters

7.8 Query the accumulated number of laser out

Send to the laser rangefinder:

Bytes	0	1	2	3	4	5
Description	0xEB	0x90	② data length (2)	0x03	0x07	Check_sum

LRF returns:

Bytes	0	1	2	3	4	5	6	7	8	9
Description	0xEB	0x90	② data length (12)	0x03	0x07	Cumulative count D31-D2 4	Cumulative count D23-D1 6	Cumulative count D15-D8	Cumulative count D7-D0	standby
10	11	12	13	14	15	16	17	18	19	20
standby	standby	standby	standby	standby	Check_sum					

When working, the LRF returns the distance and status to the host computer automatically according to the ranging frequency, and when in standby, the LRF does not return the number.